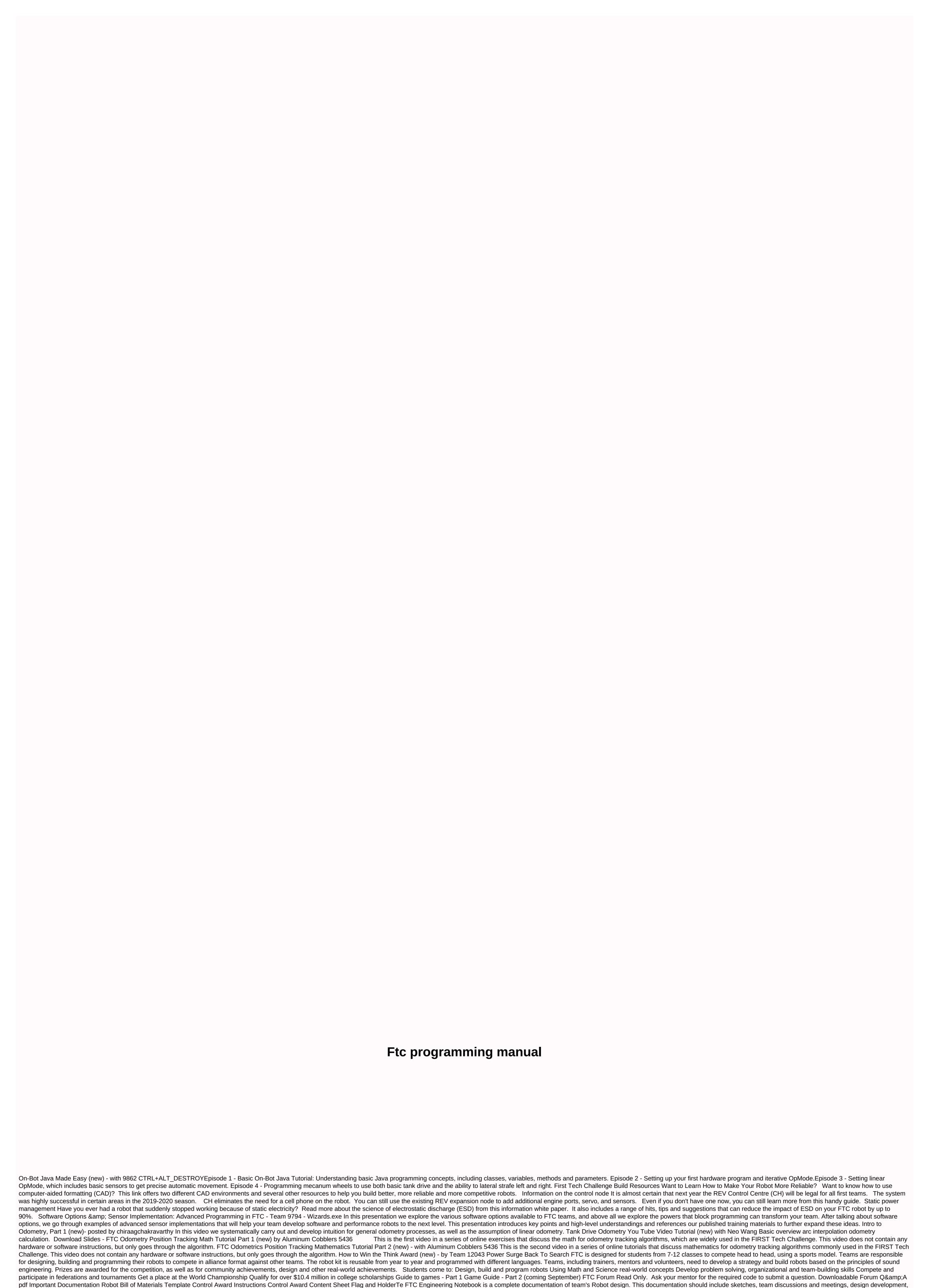
reCAPTCHA



processes, obstacles and thoughts of each team member throughout the season. A new notebook must be created for each new season. Engineering GuidelinesJava is the recommended programming language for the FIRST technological challenge. THE FIRST Tech Challenge software requires that the minimum

version used to run the program is 3.1. This includes applications and software development tools. Programming should be done using one of the following applications: 1. Blocks Programming Tool - User-friendly, graphical programming tool of a racing robot. Blocks Programming is the fastest and easiest way to start with programming. Blocks Programming One Page Description Blocks Programming Training Manual (REV Robotics Expansion Hub) Blocks Programming Training (Modern robotic hardware) 2. App Inventor Download and Resources – Teams can use a special version of the MIT App Inventor to program their racing robot. App Inventor is also a graphical design tool, and the FIRST Tech Challenge version is designed to work locally on the team's laptop. Download and Resources - Android Studio is an integrated development tool that allows teams to create Java (text-based) programs for their competing robots. Android Studio offers great flexibility when writing a program for a racing robot. Android Studio project to create THE FTC Robot Controller app) 4. Java Native Interface (JNI) & amp; Android Native Development Kit (NDK) – Teams can integrate native library codes into their applications using the JNI framework and Android NDK. Official FTC Technology ResourcesOfficial FTC Technology ResourcesOfficial FTC App Documentation*This document was created by Ken Craig not the CyberCardsAndyMark Product Spec Sheet for NeveRest 40 Motor Download File Cougar Robotics Notes on NeveRest 40 and HiTechnic Motor Controller Download FilePresentation for above discussionFTC Team Judging Session Self Reflection FTC Awards Descriptions If you have questions about specific scholarship, Contact with direct contact. Improve your search by selecting details from the filters below. Click on the scholarship provider's name to view their website Print or download the current summary list (without details) of all scholarships: FIRST scholarships listed by The State On-Bot Java Made Easy (new) - with 9862 CTRL+ALT DESTROYEpisode 1 - Basic On-Bot Java Tutorial: Understanding basic Java programing concepts including classes, variables, methods and parameters. Episode 2 - Setting up your first hardware program and iterative OpMode, which includes basic sensors to get precise automatic movement. Episode 4 - Programming mecanum wheels to use both basic tank drive and the ability to lateral strafe left and right. First Tech Challenge Build Resources Want to Learn How to Make Your Robot More Reliable? Want to know how to use computer-aided formatting (CAD)? This link offers two different CAD environments and several other resources to help you build better, more reliable and more competitive robots. Information on the control node It is almost certain that next year the REV Control Centre (CH) will be legal for all first teams. The system was highly successful in certain areas in the 2019-2020 season. CH eliminates the need for a cell phone on the robot. You can still use the existing REV expansion node to add additional engine ports, servo, and sensors. Even if you don't have it now, you can still learn more about from this handy guide. Static electricity? Read more about the science of electrostatic discharge (ESD) from this information white paper. It also includes a range of hits, tips and suggestions that can reduce the impact of ESD on your FTC robot by up to 90%. Software Options & Software options available to FTC teams, and above all we explore the powers that block programming can transform your team. After talking about software options, we go through examples of advanced sensor implementations that will help your team develop software and performance robots to the next level. This presentation introduces key points and high-level understandings and references our published training materials to further expand these ideas. Intro to Odometry, Part 1 (new)- posted by chiraagchakravarthy In this video we systematically carry out and develop intuition for general odometry processes, as well as the assumption of linear odometry. Tank Drive Odometry You Tube Video Tutorial (new) with Neo Wang Basic overview arc interpolation odometry Position Tracking Math Tutorial Part 1 (new) by Aluminum Cobblers 5436 This is the first video in a series of online tutorials that discuss math for algorithms to track odometry, which are commonly used in the FIRST Tech Challenge. This video does not contain any hardware or software instructions, but only goes through the algorithm. FTC Odometrics Position Tracking Mathematics Tutorial Part 2 (new) - with Aluminum Cobblers 5436 This is the second video in a series of online tutorials that discuss mathematics for odometry tracking algorithms commonly used in the FIRST Tech Challenge. This video does not contain any hardware or software instructions, but only goes through the algorithm. How to Win a Think Award (new) - by Team 12043 Power Surge Surge

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