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Overall View Reviews Similar Products *Note, in v1.6 the voltage scale should be set to 160 in betafight battery tab. Technical specifications: LiPo Input: 2-6S (5V-30V) Power rail: 3.3v,5v,7.2v,vbat 132A (MAX display) Current sensor with 160A PDB build in 6 layer 2oz Copper PCB Size: 36x36mm Mount Holes: 30.5 x 30.5 mm CPU - STM32F405RGT6 (F4 chip) MPU-6000 Full SD Card socket Build in 5V BEC 2A Build-in User selectable 7.2v or 5v 2A Filtered BEC For camera and VTX Dedicated Camera setting control pads along with camera power signal pads Dedicated VTX connection with along with TX4 for easy connect and control VTX Build in Betaflight OSD 4 UARTS + USB (UART1 , UART3 ,UART4, UART6) (Pinout TX1, TX4,RX4, TX6,RX6) 5V LED strip output 4 motors on each corner for a better layout. RX Support: Dedicated Inverted Sbus Hardware, Satellite RX, Ibus, TBS Crossfire Dedicated Hardware Connect to UART3 for Smart Port Telemetry 4 in 1 scket with input of TP external current sensors and Smartaudio VTX Buzzer pads for external buzzer Need hardware to mount this in your frame? Please check out this page. Important note: Electronics are not guaranteed beyond being dead on arrival. If for any reason you do not have time to check the electronics within 14 days of receipt, then no guarantee or replacement will be granted. The staff were very friendly and helpful. Claims for faulty parts by email to us after this 14-day period must be denied. 5 Published by PidiZZIE on June 15, 2018 Construction: Armattan Chameleon 5" AOKfly RV2306 2400KV Crazepony 4pcs BLHeli_32 35A ESC Dshot 1200 FRSKY XRS HOBBYMATE XT6 0 PDB AKK X1 40CH 25mW/25mW 200mW/600mW tx FPV Pagoda Antenna AOMWAY V1 GOGGLE BEATAFLIGHT 3.3.1 CLR4 Runcam Swift Quality: 5 stars - The only problem to report is that the Cam C pad was separated from the board. This may or may not have been due to my high temperature welding. There was no air conditioning in the room. Ease of use: do not #039 videos or tutorials on this board that can make it difficult for builders for the first time. A pillow design/description image is available from various sources. The design of the pillow makes all the sense and is well arranged. No additional uarts or programming steps are reassigned. It's all there. Just weld and configure it to your specifications. With patients, all levels should be able to find the answers to any questions about pillow design and function. Smaller pads will challenge your hands with experience. If you can weld this joint, you can weld anything without problem. I like to build so only change was using augmentation lens of an old set of glasses to help me see some of my work when welding bleeds on the next pillow. Easily corrected. Just check your work with an ohm meter while welding. Be prepared to buy, make a dish for this 20 mm board to 25 mm frames if you use it on anything other than a micro. I used 2mm spare carbon to make an adapter. It took 5 minutes. Programming: Flashing with Betaflight CLR4 3.3.1. I made my normal adjustments and turned on my normal OSD preferences easily as the pads were designated for ease of use. End result: Perfection. The chameleon is ridiculously sensitive when necessary and has a super smooth transition and a buttery volley. Due to the compact build size with the same function as most large FCs, I will predict that the new normal will be this FC size. I'll make a construction/flight video soon unless someone hits me at it. I don't think that anyone knows that they can use this board for a 5". Don't #039 don't be afraid to buy it now. Description Have you enjoyed full-size CL Racing FC? Or looking for a new micro-flight controller? With the current trend of reducing almost everything, CL Racing has turned its full-size FC into this mini 20x20 flight controller. With a number of features usually only found on a full size board, this mini FC gives you crazy micro build capability and feature set. It comes with rubber assembly grooves and m2 reducers to adapt to all types of constructions. Features Preedit Betaflight OSD STM32F405 @168mhz Direct Input of 2-6S MPU6000 gyro Filtered 5V and 9V BEC Direct Stack in Frsky xm+ Rx 4 in 1 ESC socket and direct welding in 4 in 1 ESC pads. Build in camera control resistor and capacitor Current sensor input welding inverter for A Sbus (in UART1), TX4 (uart4) near VTX pads for easy intelligent audio or bearing wiring 4 UARTS ---- TX6(uart6) SAT(uart6 RX), RX4 (uart4), RX3 TX3 (UART3) Direct welding 4 in 1 esc cable easy to adapt to all ESC Includes 1x CL Racing F4 Mini FC 6 Rubber Grommets 6x M2 Reducers Additional Information SKU 8402 Manufacturer CL_Racing UPC (GTIN) 736952006318 Comments Also Bought Regular Price: \$2.99 Price special \$2.24 Regular price: \$11.99 Special price \$10.79 Home > CL RACING F4 20x20 - MINI FLIGHT CONTROLLER CLR4-MFC Enjoy full size CL Racing FC lineup? Do you want to bring a similar product to the world of micros without brush? Look no further than this 20x20mm option! It has everything you expect. Specifications: Built in Betaflight OSD STM32F405 @168mhz Direct 2-6S input MPU6000 gyro leaked 5V and 9V BEC's Direct Stack in Frsky xm + rx 4 in 1 ESC socket and direct welding in 4 in 1 ESC pads. Build in camera control resistance and capacitor Current inverter welding input sensor for Sbus (in UART1), TX4 (uart4) near VTX pads for easy intelligent audio or tramp wiring 4 UARTS ---- TX6 SAT(uart6 RX), RX4 (uart4), RX3 TX3 (UART3) Direct welding 4 in 1 esc cable easy to adapt to the entire ESC package Includes: 1x CL Racing F4 Mini FC 6x Goma Grommets 6x M2 Reducers Important notes: Before welding or mounting any flight controller, connect it to the computer and verify incorrect welding techniques will damage this plate and null warranty. Please use the correct size tip, temperature and technique. Temp-controlled welding irons (such as the TS100) are available for less than \$100 and will make welding much easier. The raised pads are the result of incorrect welding techniques or excessive mechanical pressure and will not be covered under warranty. USB ports must be handled carefully, breaking USB ports are not covered under warranty Always use a smoke plug before powering your coma for the first time. 20x20mm CL Racing FC for micros without scrobrious Specifications: Built in Betaflight OSD STM32F405 @168mhz Direct 2-6S input MPU6000 gyro filtered 5V and 9V BEC's Direct Stack in Frsky xm + rx 4 in 1 ESC socket and direct welding in 4 in 1 ESC pads. Build in camera control resistor and capacitor Input current sensors welding inverter for Sbus (in UART1), TX4 (uart4) near VTX pads for easy intelligent audio or wheeler wiring 4 UARTS ---- TX6(uart6) SAT(uart6 RX), RX4 (uart4), RX3 TX3 (UART3) Direct welding 4 in 1 esc cable easy to fit all esc to remove ads between the sites of this board looks absolutely fantastic. I bought 4 of them just to install a few and see what it's all about. They arrived today and are very small and wired all on one side of the board except for LEDs. I think these pads are on your back, however, you're not sure.. Cant find more information on the board. Unlike the V5.1 nano omnibus., all the pads are on top and, in addition it has 4 uarts is crazy perfect and very large pads more is ready for cam mast control, filter 7 or 9 Volts and much more. I can't wait to cable one, tomorrow. I can't believe there's no one else writing about this FC. How can it not be fantastic? There is no one else writing about this board. So I'll tell you what I think. I wrote before this board looked awesome and I was correct. He's an awesome flight controller. Today I flew 20 packs, a frame of 120mm. This Barca is super small with tons of functionality. In this build, it had a lot of space remaining for VTX and RX.. I used the 12A 32bit 4 in 1 ESC of Little Bee so, I have ESC telemetry (temp and RPM) and, combined lipo lead with the external voltage sensor of Amass and Amperage and the build entered 90 g with close protectors as I intended to make this quad an inner flyer. I learned a day ago that an external voltage/amperage sensor is unnecessary and, Amass is not required with the ESC I deployed. The protectors nearby will leave, as soon as with the RCX 1304 5000 engines, there are power (3S) and startup was a non-brainer and even without the use of Softserial. Video filtering is the best I've seen and I'm using 5V pads and unifying 5V.. Both 5V and 9V pads are filtered according to the manual. Straight forward to the wire, wire, Easy, large bearings. I'm a beginner, too. I was not forced to add any part to get control of the camera mast and it worked very well with runcam products.. There are no Buzzer pads and that is, in fact, the only negative related to this board, however, I will live without one and the way to overcome the negatives. Now I will plan my next construction, even smaller frame because this FC allows a very small construction, but with the complete telemetry and control that, in most cases, are not available for the smaller sub class quad frames and I am, on the one hand, delighted to have this board to build and expand my fleet. I was forced to perform the investment hack on the R-XSR, but they have Lua and full telemetry. Cam Stick control and smart audio, no softserial required, you can tell, I really appreciate this board. I hope the designer sees this post, as I would like to thank you for your hard work in fe design and I would like others to buy it and discuss its constructions here. This board deserves a lot of attention for this community. Last edited by stevegross; April 16, 2018 at 12:22 AM. Vbat will power the board. I just tried this mini joint on a build of 2. The documentation does not say the capacity of the BEC to 5V and which 5V pads are filtered. The Eachine VTX03 Tx requires 3.2 to max 5.5V but when lifting the TX power to 200mW (570mA) the 5V will not be maintained. The digital screen goes into a quick blink and the image is lost. If I reduce the tx power to 50mW, usually but it doesn't always work. I wonder if I can use the 3.3V for VTX power?? There is no second UART reversed, for RunCam control. There is no ringing support. There is no 5V camera support option. (9V) Any information would be useful, Thanks. I like this board, they just don't understand the logic when splitting the Rx4/Tx4 & Rx3/Tx3 and place the relevant pads on opposite sides of the board. If you want to run anything that requires the same UART RxTx (Crossfire, GPS, Runcam Split, external black box) then you need to run cables back and forth across the board, why? the only other negative is no black box capacity. in general I still like it. does anyone figure out the bec ratings yet? received the news from the same man. 1.5A each board will make ppm? Quote: Originally published as WickedWingman received word from man himself 1.5A every stranger, told me that the Bec 5V is only 800mA This board seems to be able to do it all. I can't wait to build a long range of 3 Gecko. What uart do people use for CRSF and which one for GPS? So what is the consensus here. I have a Caddx V2 Turtle that takes 4.5-30v input and uses [email] and an AKK Fx3 that takes 7-24 input and goes up to 600mw. How do I wire it? Quote: Originally published by CalilMeTodd So what's the consensus here. I have a Caddx V2 Turtle that takes 4.5-30v input and uses and an AKK Fx3 that takes 7-24 input and goes up to 600mw. How do I wire it? I use Cam+ (pin 3) and Vtx+ (pin 8) to a Foxeer Arrow micro pro camera and an AKK Fx3 Vtx, respectively. These pins are both 9V, regulated. As you probably know, the AKK gets quite hot, like all VTX, but it's leaked 9V supply seems to handle the load well. --They had a hell of a time getting the current detection going from a 4 to 1.. Any photos of wiring? Page 2 Hello everyone! I'm just up to buid with CLRacing F4 Mini. I understand that there are no external B+ and B pads. Is there any other way to connect an external bell to this? If not, I have tried to configure esc page 3 The Hitec HS-788HB servo is based on the longtime favorite, the HS-785HB. This new model was created with a 25-tooth output line in order to fit most of the servo hobby market. Market.

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